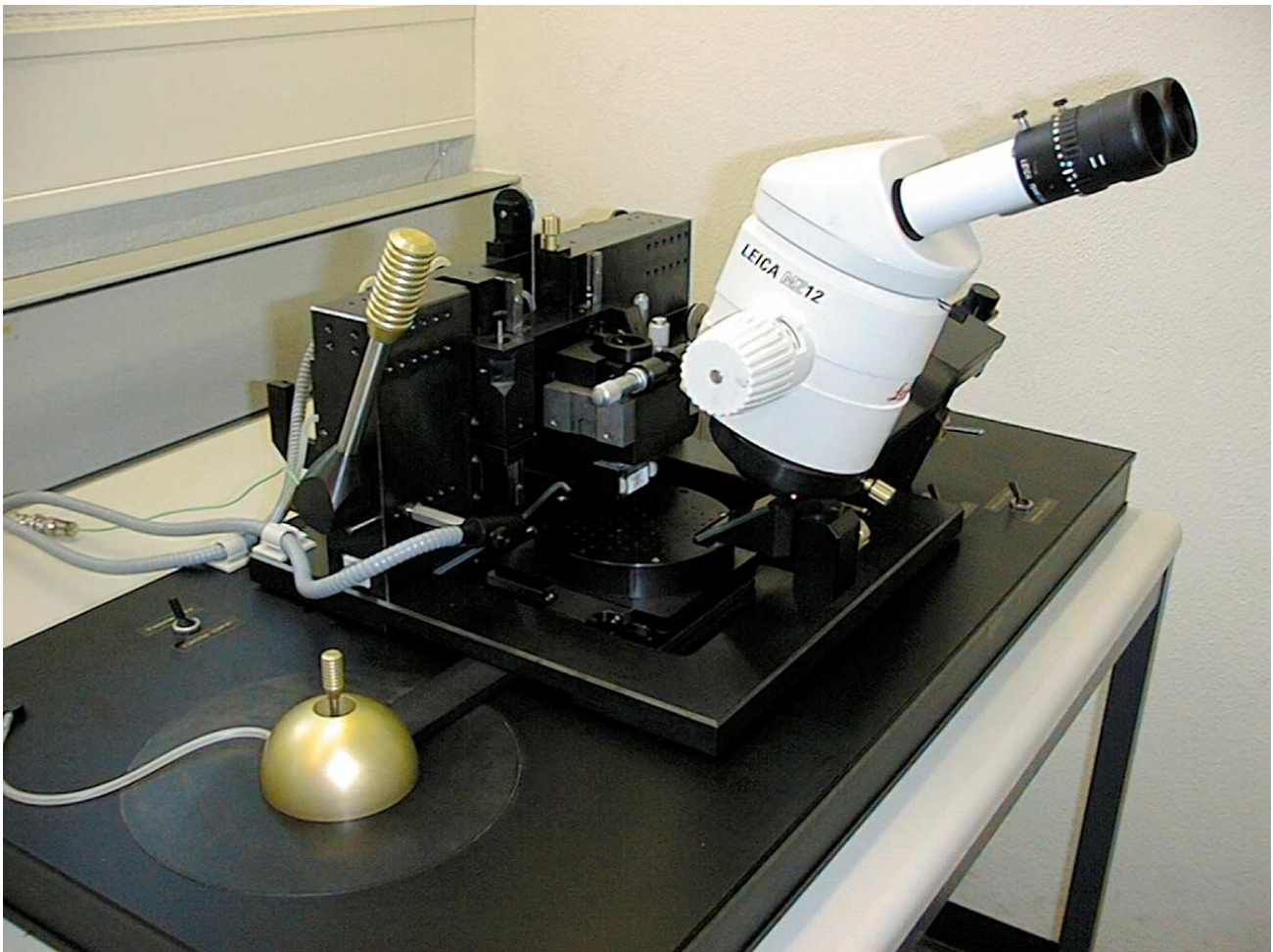


Status of PSI bump placer

- Manual bump bonder
- Why automation
- First concept
- Actual design
- Outlook

Old bump bonder

- Positioning of sensor
- Rotation of chip
- Prism allows view chip and sensor.

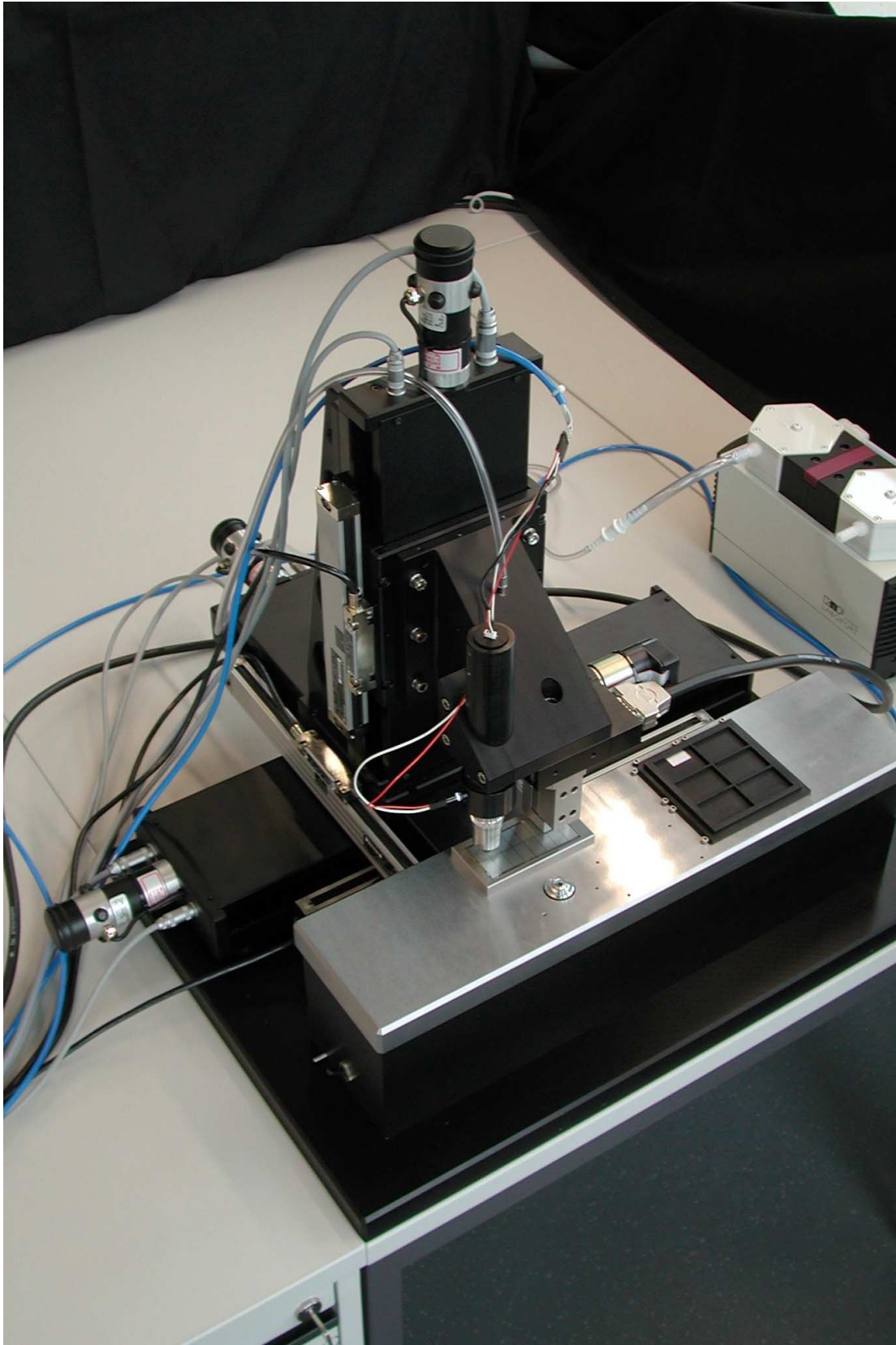


Old bonder – new bonder

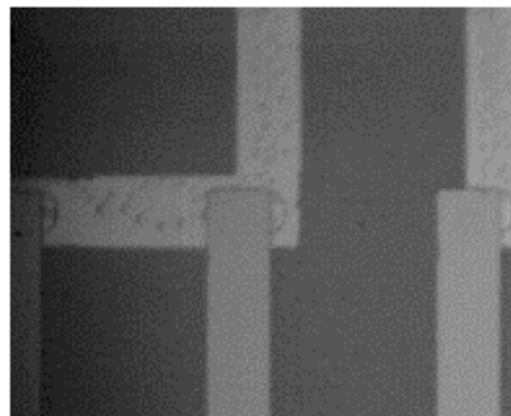
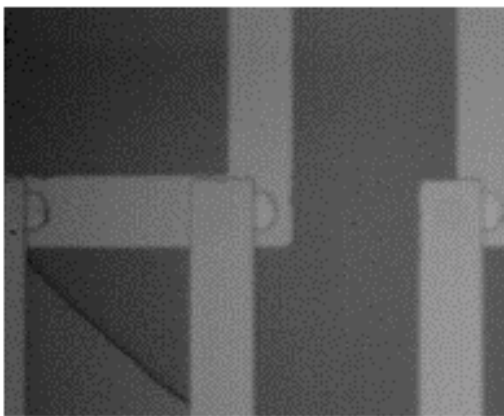
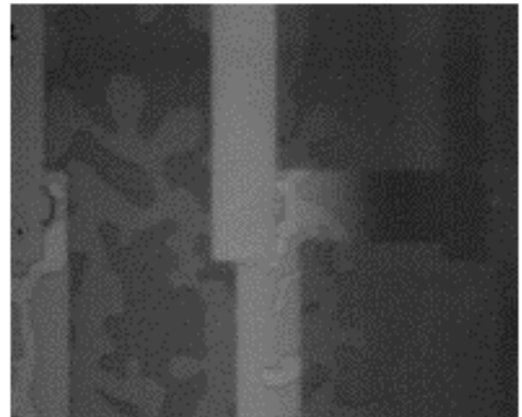
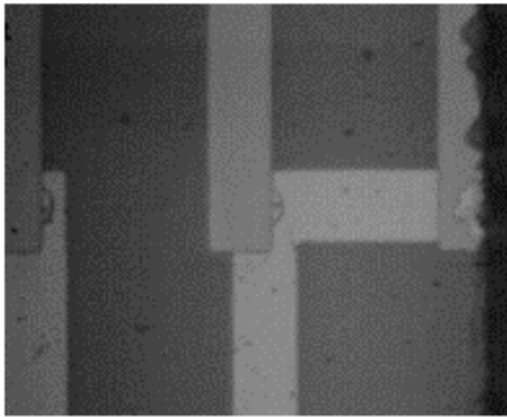
- 1-3 hours for trained person (16 chips).
- Always looking through microscope.
- Around every 10th module has a displaced chip.
- 30 min (4 chips).
- Image is on monitor.
- Pattern recognition allows higher grade of automation. No operator needed after start.

Only with automation ~800 CMS pixel modules can be produced within 2 years

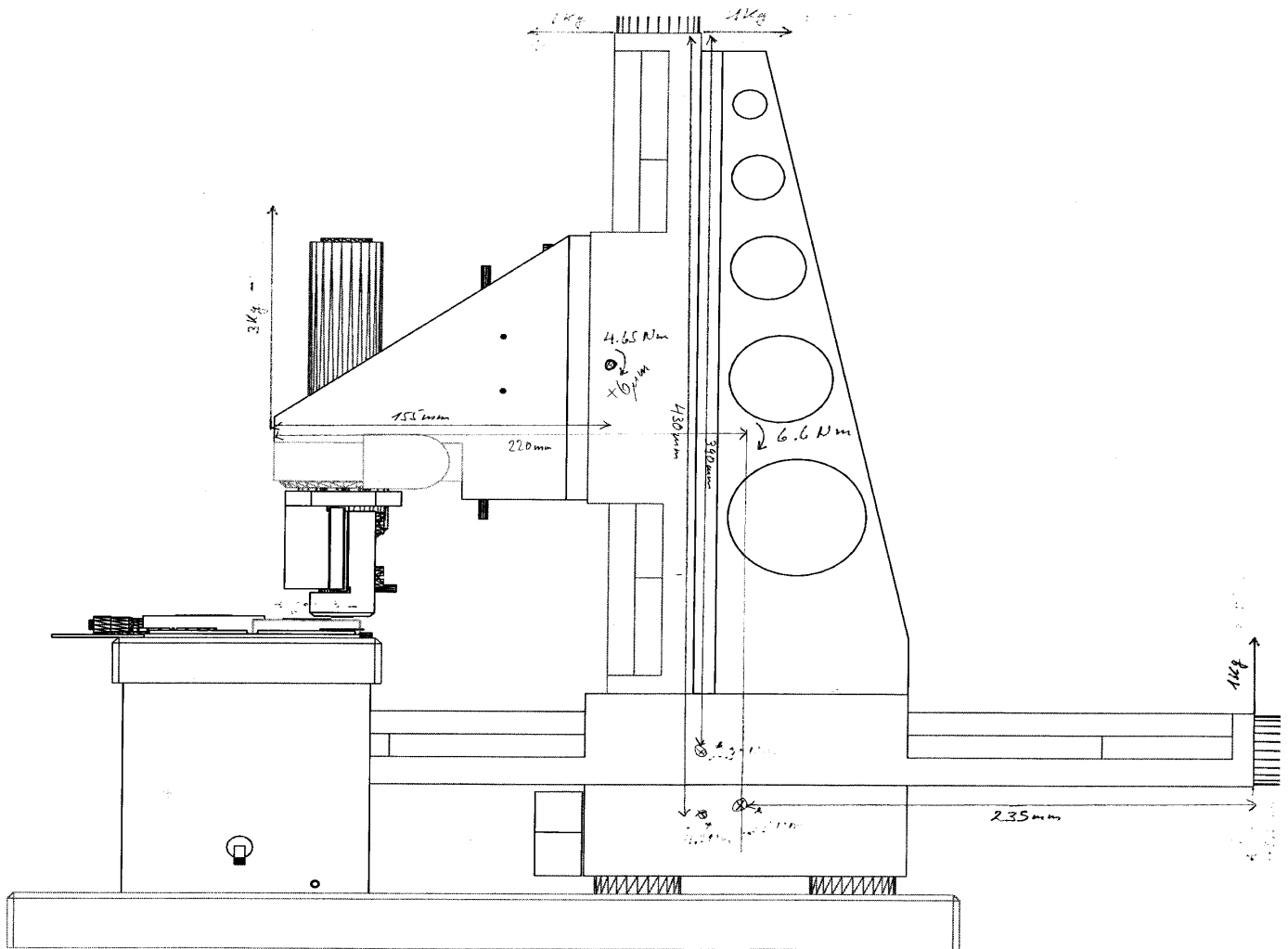
First concept



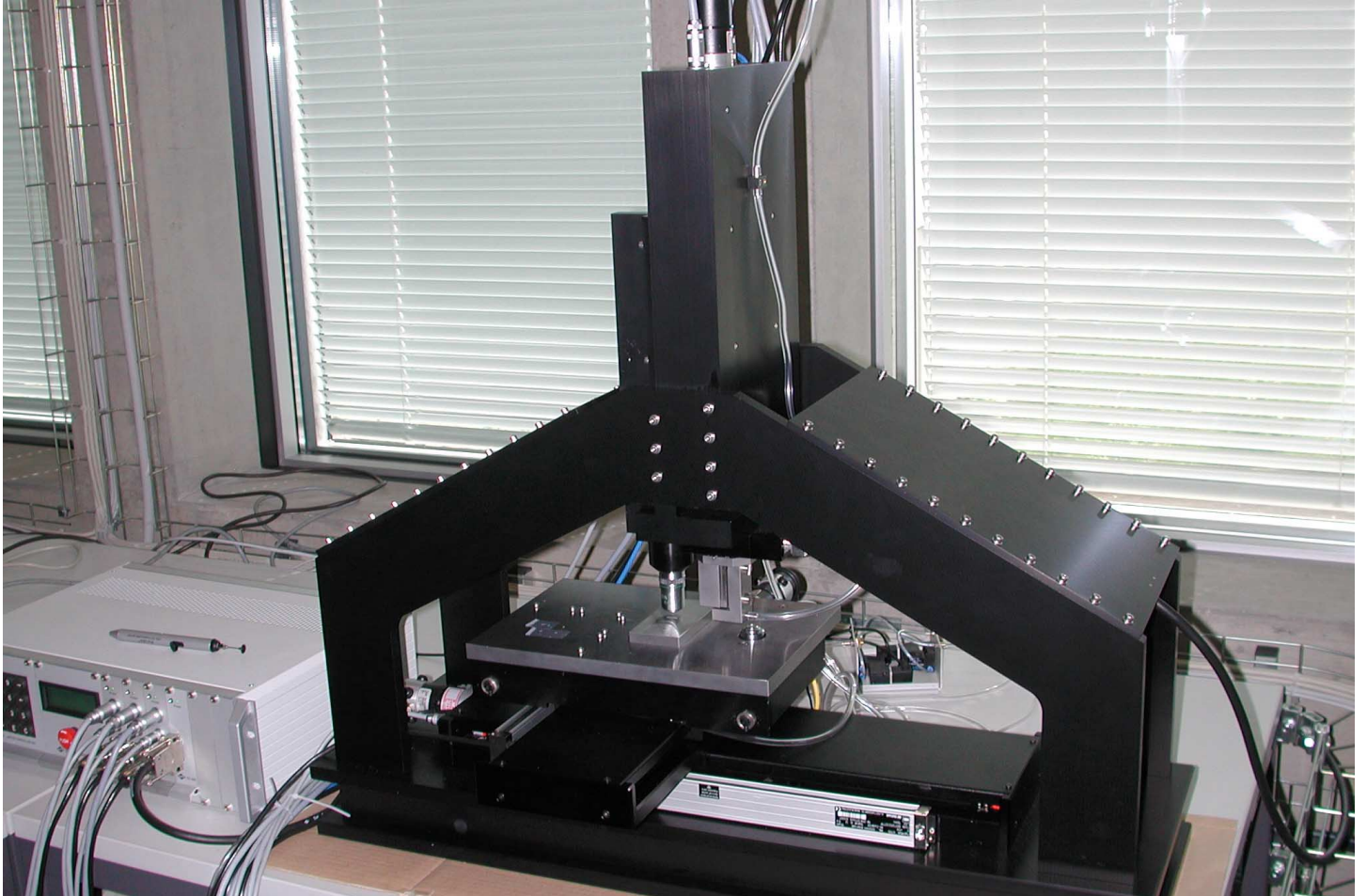
Placing of glas structures



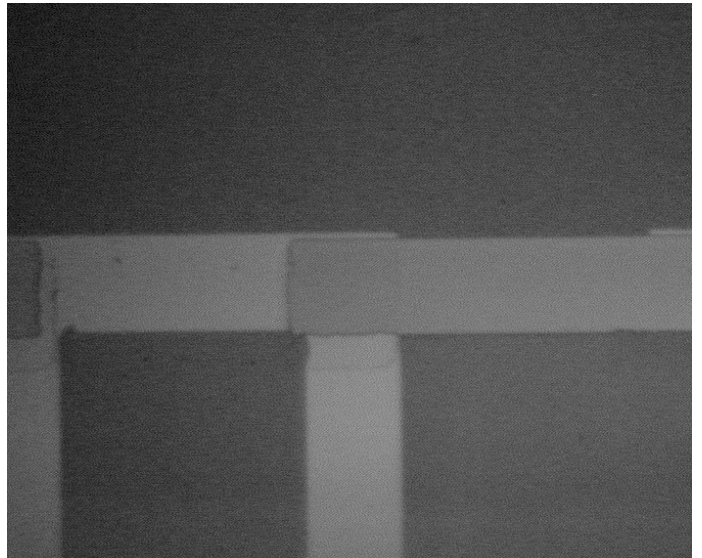
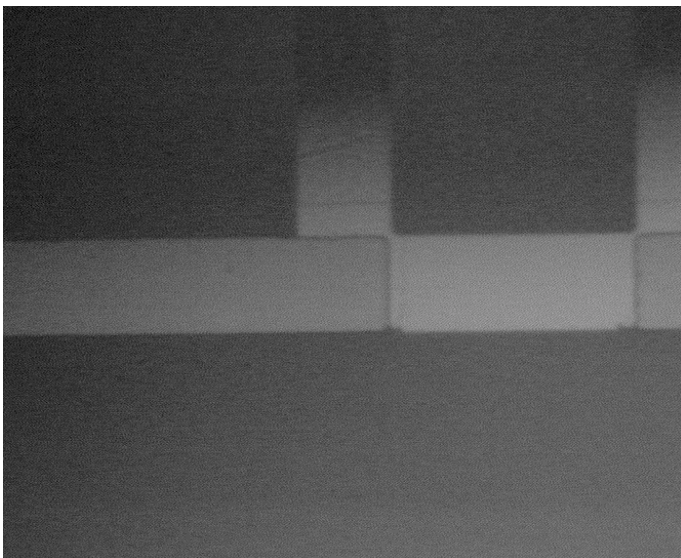
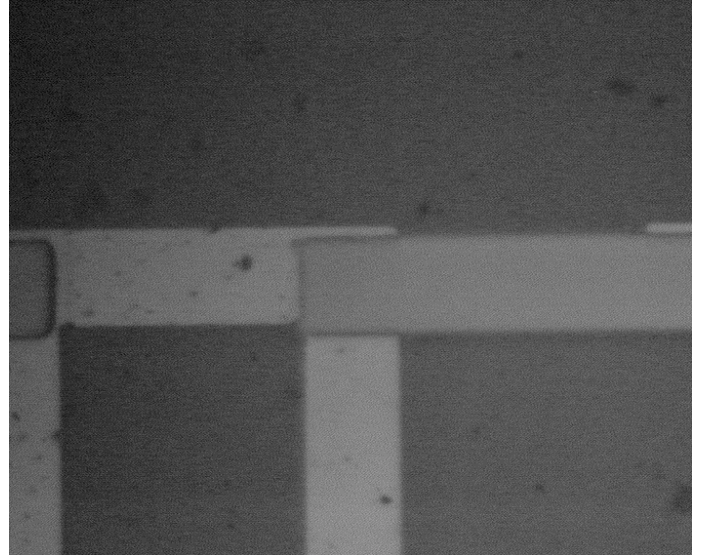
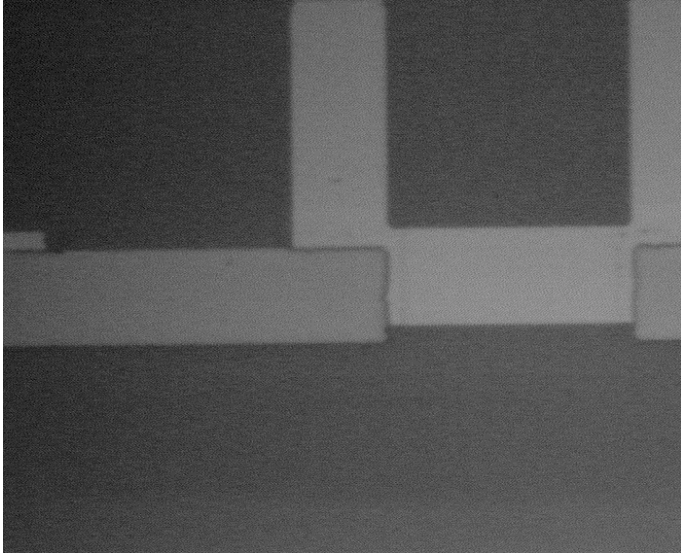
Force test



Second concept



Placing with new bonder



Accuracy ~ 5 μm

Outlook

- Calibration of motor stages.
- Start bonding